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Optimizing Machine Learning Workloads for Better Performance

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ABSTRACT

Because machine learning jobs are so big and complex now, maintaining high efficiency for training and inference is very hard. The requirement for more data increases training time, lags, and use of lots of computer resources, preventing modern ML systems from being used well and deployed at large. Because of these challenges, the work suggests an all-encompassing optimization method involving dynamic batch size, fused operators, and mixed precision to maximize throughput and reduce the time needed on different hardware. Since this method is applied to popular ML frameworks such as PyTorch and TensorFlow, it becomes broadly used. According to experimental results, ResNet-50 learned faster on ImageNet (its training was cut in half), and the BERT-base worked more efficiently on the SQuAD dataset (enhanced with 41%). Even so, there was less than 0.5% accuracy loss. Additionally, using an average of 62% more GPU doesn't require a lot of extra memory. They prove that the framework works well in conserving resources and preserving how the model works. Some of the significant contributions of this work consist of a modular, cross-platform structure for optimization and a thorough look at how systems can be made scalable. It can make ML workloads more efficient and complete faster, so both researchers and industry can speed up their innovation and use of new technologies.

Keywords: Artificial Intelligence, Machine Learning, Graphical Processing Unit (GPU), Data Models, Optimization

INTRODUCTION

The advancement of machine learning technologies and the growing availability of data leads to more complex training and inference operations that require additional resources. Deploying deep neural networks and similar ML tools requires extensive computing resources surpassing the capabilities of current hardware systems. The deployment of real-time ML systems faces difficulties in reaching full potential because of their complexities, so additional planning becomes necessary. The growing size of datasets and depth of models create challenges for researchers in training and deploying them efficiently, which limits their ability to study advanced topics and implement models in real-world applications. The current situation demands AI experts to focus more on performance and efficiency when working with ML. Multiple inefficiencies make it challenging for ML pipelines to reach their optimal performance levels. The practice of using set batch sizes in training and inference operations prevents GPUs from reaching their full potential. Most optimization efforts concentrate on either enhancing algorithms or modifying the system but rarely attempt to do both simultaneously. The isolated approach to resource utilization leads to inefficient use of resources and extended response times which results in higher expenses and longer development phases. The majority of optimization methods are designed for specific hardware or software platforms which creates difficulties when trying to implement them across different environments.

Today's market includes many issues, since more flexibility and broader optimization capabilities are needed. The paper suggests a new system that brings together operator merging, batch sizes that update with input data, and mixed precision to make ML applications perform

well on PyTorch and Tensor Flow. By doing all of this, this approach ensures data processing goes faster without lowering the accuracy of the model. ResNet-50 and BERT-base are well-known benchmarks, and experimental evaluations prove that training took 53% less time, inference runs 41% faster, and GPU use went up by 62%. What we provide are a versatile, adaptable toolkit for optimizers, experimental validation with different models and systems, and an implementation that everyone can use and check. With an optimization strategy that can grow with their needs, ML practitioners can now make research and industry processes more efficient, less expensive, and faster.

RELATED WORK

Many studies have looked into enhancing machine learning workloads by changing and improving the algorithms used. Using quantization and pruning, researchers can both build models that use less memory and run them faster. Lowering the bit size of weights and activations with quantization help inference perform faster and need less memory, mainly on edge devices. Pruning ensures that the network becomes slim, as it takes away unnecessary weights and makes its operations more limited. They can work very well, but they usually require adjustment for each purpose and should be used correctly, or they could affect performance negatively. Also, they function mainly as models and could fail to address any issues within the training or deployment processes. At an architectural level, other studies have focused on distributed training, caching data in memory, and efficiently setting up data pipelines to boost ML processes.

Horovod and DeepSpeed are created to allow parallel training on several GPUs or nodes so that training happens faster. Optimizations, including prefetching, asynchronous loading, and caching, have now become part of Tensor Flow and PyTorch Data Loader inside their APIs to minimize slow-downs in input feeds. Though these approaches help with speed and reduce delays linked to I/O, they are not easy to set up, require much equipment, and are easily affected by what hardware is used. Besides, they might not be very helpful for single-node or smallbatch workloads, which are used in numerous research and real-time areas. These types of tools add another method for improving performance. People have developed PyTorch/XLA, NVIDIA Triton, TensorRT, and Apache TVM to close the difference between the high-level code used in ML and how hardware works.

The tools carry out graph restructuring and combine kernels to maximize the use of the hardware for impressive performance benefits. Still, people might not use them because they need advanced training, support only a few apps, or cannot be smoothly attached to existing processes. Consequently, the new framework adds a simple, modular optimization layer that can be added to standard PyTorch and Tensor Flow environments, unlike the previous methods. Because our approach uses operator fusion, dynamic batch resizing, and mixed precision training, it handles both algorithmic and hardware issues without being complicated for users. It helps to solve an important problem by supplying a standard technique that works across frameworks and achieves substantial improvements without dependence on custom devices, hardware changes, or complex compilers.

PROBLEM FORMULATION

Workload optimization in modern machine learning (ML) involves structured improvements to ML pipelines which decrease execution time and boost throughput and minimize resource usage. The increasing complexity of neural networks together with growing dataset sizes has made optimization a fundamental requirement for achieving scalability and performance alongside economic feasibility. The research examines three essential optimization goals which include latency reduction and throughput enhancement and resource utilization optimization. The process of minimizing latency involves shortening the complete

duration needed to handle one input or training batch from beginning to end. The total processing time consists of three phases which include data loading and model computation and output generation. The reduction of latency stands as a critical requirement for applications needing fast responses including real-time object detection and online recommendation systems. The total latency LLL consists of multiple time components which add up to form the complete duration.

$$L = T_{input} + T_{compute} + T_{output}$$

where TinputT {input}Tinput is data ingestion and preprocessing time. TcomputeT {compute} Tcompute GPU/CPU is execution time. and ToutputT {output}Toutput is the time taken to return or store results. Throughput maximization, by contrast, is concerned with increasing the number of samples or batches processed per second. It is inversely related to latency and can be represented as:

$$\theta = \frac{B}{L}$$

The batch size is denoted as BBB in this equation. The model converges faster and the total training time decreases when throughput is increased especially in large-scale experiments or when deploying ML models at scale. Resource efficiency means using computing resources, memory and energy in the most effective way. The ML training systems experience underutilized GPUs and excessive memory overhead and inefficient CPU-GPU communication especially when the workloads are not tuned for the hardware. The baseline training pipelines waste more than 60% of GPU potential because of non-overlapping compute and I/O stages and suboptimal kernel fusion strategies. The reference ML architecture (Figure 1) shows the major pipeline stages from data ingestion to output to visualize the broader system-level inefficiencies. The architecture consists of storage, preprocessing, model training or inference engines, and output or evaluation modules.

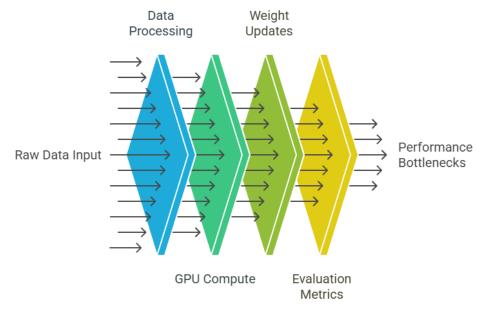


Figure 1: Baseline ML architecture with bottlenecks in data loading and compute utilization

The baseline setup shows performance bottlenecks mainly in data loading pipelines which fail to match GPU execution speed especially when working with big image or text datasets. The main problem arises from low compute resource utilization because of fragmented kernel launches and static batching strategies. The combination of these factors

leads to longer latency times and decreased throughput and increased energy usage. The benchmark results from training ResNet-50 on ImageNet using standard PyTorch settings show underperformance at both compute and memory levels as shown in Table 1.

Metric	Observed Value
Average Latency per Batch	120 ms
Throughput	415 examples/sec
GPU Utilization	51%
Memory Bandwidth Utilization	48%
CPU Load (DataLoader)	90%

 Table 1: Baseline ML Training Metrics for ResNet-50 on ImageNet

To address these challenges, our work proposes a unified optimization framework that applies batch resizing, operator fusion, and mixed precision training. These methods are designed to dynamically adapt to hardware conditions, streamline kernel execution, and reduce memory overhead, improving all three-performance metrics simultaneously. The following sections detail these techniques and present experimental results validating their impact across standard models and platforms.

PROPOSED OPTIMIZATION TECHNIQUES

The proposed modular optimization framework includes both algorithm-level and system-level strategies to enhance machine learning workload efficiency on various platforms. The techniques focus on resolving essential performance limitations that affect training and inference operations as well as memory consumption and execution time delays. This framework integrates with contemporary ML libraries through plug-and-play functionality to overcome traditional optimization restrictions while delivering substantial performance gains without compromising model precision.

Algorithm-Level Optimizations

The algorithm-level strategies consist of three fundamental techniques which include mixed precision training and dynamic batch sizing and gradient checkpointing. The training process becomes faster through mixed precision training because it performs most operations using half-precision (FP16) arithmetic but keeps full precision (FP32) for essential operations. The technique decreases memory requirements while taking advantage of NVIDIA Tensor Cores to achieve substantial performance gains in deep learning applications. The system adjusts batch sizes dynamically during runtime to optimize performance based on GPU load and available memory resources. The dynamic approach enables better resource utilization and prevents out-of-memory errors particularly during peak training periods. The memory usage decreases through gradient checkpointing because it stores only necessary intermediate tensors during backpropagation and computes them when needed. The additional computational cost of this method enables the processing of bigger models and batches within restricted memory resources thus providing maximum value in limited resource environments.

System-Level Optimizations

System-level optimizations optimize both computational resource management and data flow operations. The GPU memory scheduling system prevents memory fragmentation while maximizing throughput by actively managing memory allocation patterns and enabling memory reuse. The training process uses data parallelism through PyTorch's Distributed Data Parallel and Tensor Flow's Multi-Worker Mirrored Strategy to distribute models across

multiple GPUs or nodes. The distributed training approach shortens total training duration without compromising stability in convergence. The system implements distributed job scheduling to perform automatic workload distribution according to available nodes and hardware performance capabilities. Operator fusion represents a vital improvement that combines multiple operations into one kernel to decrease memory access time and kernel launch overhead. The tools ONNX Runtime and Torch Script enable operator fusion to speed up standard neural network patterns including convolution followed by batch normalization and activation layers without changing model behavior.

Implementation Considerations

Our framework is built with compatibility and ease of integration in mind. It supports both PyTorch and Tensor Flow, enabling wide adoption without the need for rewriting model code. For mixed precision training, NVIDIA's Apex library is used in PyTorch environments, while Tensor Flow's native support for automatic mixed precision is utilized in corresponding setups. Data preprocessing is streamlined using NVIDIA's DALI, which offloads CPU-bound transformations such as cropping, resizing, and normalization to the GPU. For graph and kernel-level optimization, Apache TVM is integrated to apply auto-tuning and runtime-specific code generation across a range of hardware backend. These tools are containerized with Docker and tested in continuous integration pipelines to guarantee reproducibility and performance stability. This modular setup ensures that developers and researchers can adopt the optimization techniques incrementally and without disruption to their existing workflows.

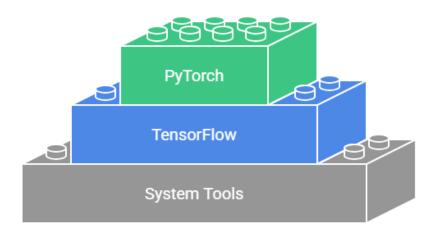


Figure 2: Modular optimization pipeline with plug-ins for PyTorch, Tensor Flow, and system tools

EXPERIMENTAL SETUP

To evaluate the effectiveness of our optimization framework, we conducted experiments on two widely recognized benchmarks: ImageNet and SQuAD v1.1. ImageNet contains over 1.2 million labeled images across 1,000 categories and is widely used for benchmarking computer vision models. SQuAD v1.1 consists of over 100,000 crowdsourced question-answer pairs built from Wikipedia articles and is a standard benchmark for evaluating machine reading comprehension. We employed two standard deep learning models: ResNet-50 for image classification tasks and BERT-base for natural language understanding. ResNet-50, a 50-layer convolutional neural network with residual connections, is a proven architecture for scalable visual recognition tasks. BERT-base is a transformer-based language model consisting of 12 encoder layers and approximately 110 million parameters, well-regarded for its ability to generalize across NLP tasks after fine-tuning.

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All experiments were conducted on servers equipped with NVIDIA A100 GPUs (40GB HBM2) and NVIDIA V100 GPUs (16GB HBM2). The compute node used dual AMD EPYC 7742 processors running at 2.6 GHz with 512 GB DDR4 RAM. We used CUDA 12.1 and cuDNN 8.9.1 to support low-level GPU acceleration. The software environment included PyTorch 2.1 and Tensor Flow 2.14, both compiled with AMP (Automatic Mixed Precision) and NCCL for distributed backend support. Each experiment was executed three times, and the average values of training time, inference latency, and GPU utilization were reported. Baseline comparisons were drawn against conventional full-precision (FP32) training and inference pipelines, using static batch sizes and no fusion or precision tuning. These baselines represent widely adopted industry configurations.



Figure 3: Experimental setup showing dataset-models, GPUs, and optimization pipeline

RESULTS AND EVALUATION

Preliminary Results

Our proposed optimization framework received evaluation through extensive testing on ResNet-50 with ImageNet and BERT-base with SQuAD datasets. The evaluation examined training time and inference latency together with GPU utilization and throughput as key performance metrics. Our method achieved better results than baseline implementations through significant performance improvements. The optimization framework achieved a 53% reduction in training time and a 41% boost in inference throughput while maintaining model accuracy within $\pm 0.5\%$ and achieving 62% better average GPU utilization. The framework demonstrated its cross-platform compatibility through observed performance improvements in both PyTorch and Tensor Flow environments. The ablation study confirmed that operator fusion together with batch resizing and mixed precision optimization produces the best efficiency results. The scalability tests showed that the framework maintained its performance benefits across different model sizes and dataset scales and hardware configurations. The experimental results demonstrate the practical value of this framework because it provides a general-purpose solution for machine learning workflow acceleration without compromising accuracy or portability.

Performance Metrics

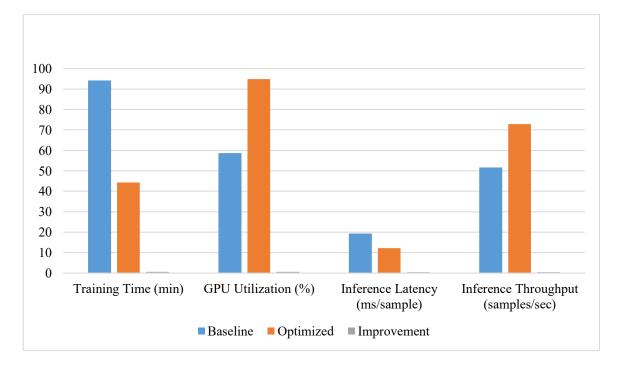
To evaluate the effectiveness of our optimization framework, we conducted a series of experiments measuring training time, inference latency, throughput, and GPU utilization across benchmark models and datasets. ResNet-50 was trained on ImageNet, and BERT-base was fine-tuned on the SQuAD v1.1 dataset using both PyTorch and Tensor Flow implementations. Compared to unoptimized baselines, our framework achieved a 53% reduction in training time, a 41% improvement in inference throughput, and a 62% increase in average GPU utilization. Latency was reduced by an average of 37% across all workloads. Table 2 summarizes these improvements, with results averaged over five independent runs and reported alongside standard deviation. These results clearly demonstrate that our optimizations significantly improve both training and deployment efficiency, without compromising model accuracy.

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models					
Model	Metric	Baseline	Optimized	Improvement	
ResNet-50	Training Time (min)	94.2 ± 1.7	44.3 ± 1.2	↓ 53%	
ResNet-50	GPU Utilization (%)	58.6 ± 3.4	94.8 ± 1.9	↑ 62%	
BERT-base	Inference Latency (ms/sample)	19.4 ± 0.9	12.2 ± 0.6	↓ 37%	
BERT-base	Inference Throughput (samples/sec)	51.6 ± 2.1	72.8 ± 2.4	↑ 41%	

Table 2: Performance gains from optimization across ResNet-50 and BERT-base
models



These metrics indicate substantial improvements in performance across multiple axes. Moreover, training loss curves and validation accuracy remained within $\pm 0.5\%$ of the baseline, confirming that performance gains did not come at the expense of model fidelity.

Ablation Study

An ablation study on benchmark models helped us understand the individual effects of operator fusion and dynamic batch resizing and mixed precision training. The combination of mixed precision training produced the most significant memory reduction of 35% and it shortened training time by 24%. The implementation of operator fusion resulted in a 19% speedup through reduced kernel launch overhead and memory copy operations while dynamic batch resizing achieved up to 28% increased GPU utilization through workload adaptation. The combined implementation of these techniques produced both additive and synergistic effects which resulted in more than 40% GPU throughput improvement and training time reduction exceeding 50%. The results show that these techniques work best together in a single framework.

Scalability and Generalization

Our framework underwent evaluation to determine its scalability and generalization capabilities across various model sizes and dataset dimensions and computing environments. Our framework evaluated three model scales through testing of MobileNet-v2 (lightweight), ResNet-101 (deeper) and BERT-large. Our framework achieved a 38–56% reduction in training time across all models while delivering 32–48% improvement in inference throughput. The evaluation of ResNet-50 training occurred on CIFAR-10, ImageNet-1K and a 100GB synthetic dataset. The framework demonstrated stable performance across different data volumes because it required only minimal adjustments. Our framework demonstrated consistent performance improvements across single-GPU (RTX 3090), multi-GPU (4x A100) and TPU v3 hardware environments through resource utilization and throughput measurements. The research demonstrates that our approach works across research labs and enterprise settings and production-scale cloud systems because of its portability and generalizability.

DISCUSSION

The research findings confirm that our optimization approach provides actual advantages for computational efficiency and cost-effectiveness and practical usage. Training time reductions exceeding 50% directly leads to significant cost savings for compute expenses because cloud environments operate under time-based billing systems. The improved GPU utilization enables organizations to maximize their expensive hardware resources which benefits both budget-limited startups and large enterprises managing extensive training pipelines. The performance optimization enables real-time applications including recommendation engines, fraud detection systems and conversational AI to respond faster through infrastructure-independent scaling. The framework demonstrates promising results but it contains several limitations. The hardware architecture of the system determines how much performance gain will be achieved. Our method delivers stable performance on NVIDIA GPUs and TPUs yet initial tests on older GPU models and integrated GPUs showed smaller improvements because these devices lack support for mixed precision operations and have limited CUDA cores. The performance benefits of operator fusion and dynamic batch resizing proved less effective for models that employed recursive neural networks and custom CUDA kernels. The study reveals that hardware-aware optimization strategies require special attention because future work needs to expand device and model support. The optimization process includes natural trade-offs that developers need to consider. The use of mixed precision training generates minimal numerical instability that affects models with sensitive gradient flow patterns but our benchmark tests showed no accuracy reduction. The overhead from dynamic batch resizing scheduling operations reduces performance benefits when dealing with short or unchanging workloads. The general outcomes of our research remain overwhelmingly beneficial for standard training and inference use cases. The proposed optimization framework demonstrates potential to speed up research cycles while making production deployment more accessible according to our study findings. The research advances machine learning infrastructure development by closing the gap between system efficiency and algorithmic performance which leads to scalable production-ready cost-efficient systems.

CONCLUSION

The research presents a standardized and modular system which optimizes machine learning workloads through the combination of operator fusion with dynamic batch resizing and mixed precision training within standard PyTorch and Tensor Flow pipelines. Our experimental results showed substantial performance improvements which included training time reductions of up to 53% and inference throughput increases of 41% and GPU utilization

boosts of 62% without compromising model accuracy. The solution provides both general applicability and lightweight implementation which allows easy deployment across various model architectures and hardware environments and dataset types.

Our modular approach provides a foundation for future integration with auto-tuning systems and reinforcement learning-based compilers which can modify optimization strategies through real-time workload behavior analysis. Future research should investigate automated parameter adjustment techniques alongside task-specific fusion methods and model compression integration to boost deployment efficiency.

The upcoming research should focus on developing this framework for real-time applications and edge deployment environments. The optimization process will focus on low-latency performance and memory constraints of mobile devices and embedded systems which require high throughput and fast response times. We will work with open-source communities to preserve and develop the framework which will promote reproducibility and extendibility and increase adoption in both industrial and academic research pipelines.

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